

Elevator calculation acc. EN81-20/50

**Elevator data**

Nominal load	Q	kg	630	
Car weight	F	kg	750	(701 - 1057kg)
Counterweight	G	kg	1065	(50%)
Travelling speed	v	(V_3=)	m/s	1.00
Travel distance	H	m	30.0	
Suspension / (roping)	is			2 : 1
Machine at the top, above				
Shaft efficiency	etaS	%	82	
Number of pulleys	(ball bearing)		3	
Type of rope	WOLF F 819 S-FE			
Number of ropes	z		5	
Rope diameter	ds	mm	8	
Rope weight	s	kg	32	(0.215 kg/m)
Compensation rope weight	su	kg	0	
Car cable weight	HK	kg	15	
Rope span weight	R	kg	0	
Min. rope breaking load	B	N	30500	
Traction sheave diameter	Dtr	mm	320	
Sheave width		mm	110	(number of grooves

6)

Groove distance		mm	17.0	Standard
Angle of wrap minimum	min.	deg	180	
Undercutangle		deg	95	
Undercutwidth	b	mm	5.90	
Groove angle		deg	30	

Sheave profile: circular undercut groove

**Traction, rope pressure, rope safety**

Traction empty, on top, accelerating (1.18)  
 1.7387 <= 1.8399  
 Traction 150% nominal load, below, not moving  
 1.6521 <= 1.8399  
 Rope pressure k < permissible rope pressure  
 6.14 < 9.00 N/mm<sup>2</sup>

Conditions according to EN81-1 or -20:  
 Load 125% 1.5042 <= 1.8582 (1)  
 Emergency stop 1.6396 <= 1.6759 (4)  
 with deceleration [m/s<sup>2</sup>] 0.500  
 Blocked car 14.643 > 3.4528 (4)

Real safety factor > Minimum safety factor for ropes  
 21.52 > 12

Rope safety factor according to EN81-1 or -20:  
 NEQUIV = 08.7 NEQUIVT = 06.7 NEQUIVP = 02.0  
 Pulleys >= 320 mm, pulleys NPR = 0 NPS = 2  
 Rope safety nue = 21.5 > 17.8 (minSF)

Rope certification EN81

Traction conditions are fulfilled.

Rope safety conditions are fulfilled.

**ZAlift - 20160710 - Machine dimensioning f8792077**

### **Mechanical drive data**

Machine manufactured by Ziehl-Abegg

Machine type SM 200.20C Gearless synchronous

Machine version ZAtop \*

Traction sheave mm 320 /110/17.0/6x8/U95

Load output torque Nm 361 (max. 396)

Real statical axle load kg 1262 (max. 2440)

### **Brake data**

brake Mayr ROBA-twinstop 350, 2x410, EU-BD 845 (ABV845 + ESV845)

Dual circuit disk brake, DC supply necessary

EC type-examination, release monitoring (298 Nm, 0.54 m/s<sup>2</sup>, 1 m, 6281 J, 164 W)

2 x 410 Nm 207 V brake, without hand release

### **Machine load data in the installation**

Typical motor operating power kW 2.8

Typ. operating current 18.8 A, Start. Current 27.9 A at acceleration 0.60 m/s<sup>2</sup>

Start. Current 29.4 A at acceleration 0.7 m/s<sup>2</sup>

Average power losses 0.66 kW = 2393.07 kJ/h

Output speed rpm 119

Load torque Nm 361.1 (eff. 226.6)

Inertia of installation kgm<sup>2</sup> 16.47

240 Starts per hour, 40 % required duty cycle at elevator operation

Max. static load pulleys 10447 N, pulley speed 1.00 m/s

### **Selected ZIEHL-ABEGG motor**

Motor type SM200.20C-20 - gearless

	Nameplate data	(Operating
data)		
Rated voltage	V 360	
Rated frequency	Hz 28	( 19.9)
Rated torque	Nm 330	( 361.1)
Rated speed	rpm 168	( 119.4)
Rated output power	kW 5.8	( 4.5)
Rated current	A 16.5	( 18.8)
Maximum torque	Nm 570	( 570 )
Current at maximum torque	A 34	( 34 )
Inertia of motor	kgm <sup>2</sup> 0.160	
Possible acceleration	m/s <sup>2</sup> 1.00	
(MKmax=280.0 Nm)		
Without cooling	(83)	

Dimension sheet A-M-6445 / A-M-6451, Motor construction type IMB3  
Motor with encoder ECN 1313-2048Endat

### Selected frequency inverter

Inverter ZAdyn 4CS017, Rated inverter current 17 A  
mains current 11.6 A, 400 V, 7.6 kW, Max.  $0.78 \text{ m/s}^2$ ,  $F_{amax} 1.63$  (513 Nm)  
Radio interference filter, integrated ; Line reactor, integrated  
Brake resistance separate BR17-3 (or Recuperation: ZArec4C 013)  
**ZAlift - 20160710 - f8792077**

### Elevator data

Elevator	630kg-1.00m/s-2:1-30m
Machine type	SM 200.20C
Traction sheave	320/110/17.0/6x8/U95
Inertia Traction sheave	0.727 kgm <sup>2</sup>

### Brake data

Mayr ROBA-twinstop 350, 2x410, EU-BD 845 (ABV845 + ESV845), 35 ms, 60 ms, 90 ms  
2 x 410 Nm 207 V brake, without hand release

### Calculation of unintended movement (EN81-1/A3)

#### Values of elevator controller

Detection distance	0.050 m
Dead time	50 ms
V Detector	0.000 m/s

#### without short-circuit motor braking

	a [m/s <sup>2</sup> ]	s [m]	v [m/s]	t [s]	
1:	4.80	0.05	0.69	0.14	
2:	4.80	0.09	0.93	0.19	
3:	1.72	0.12	0.99	0.23	
4:	0.86	0.14	1.01	0.25	
5:	-0.31	0.15	1.01	0.26	
6:	-0.62	0.97	0.00	1.89	

Stopping distance (without influence of traction)	0.320 m, empty up
Max. stopping distance (depending on traction)	0.972 m, empty up
Max. stopping distance (depending on traction)	0.476 m, full down
Max. stopping distance (inverter off, empty car)	0.310 m, empty up
Max. test stopping distance (v= 0.150m/s)	0.108 m, empty up
Max. test stopping distance (v= 0.150m/s)	0.096 m, full down
Max. test stopping distance (a= 2.000 m/s <sup>2</sup> )	0.356 m, empty up
Max. test stopping distance (a= 2.000 m/s <sup>2</sup> )	0.266 m, full down

**We assume no liability for calculation results!**